

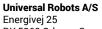
## Technical specifications UR10

Item no. 110110

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## 6-axis robot arm with a working radius of 1300 mm / 51.2 in

Weight:	28.9 kg / 63.7 lb
Payload:	10 kg / 22 lbs
Reach:	1300 mm / 51.2 in
Joint ranges:	+/- 360°
Speed:	Base and Shoulder. 120°/s. Elbow, Wrist 1, Wrist 2, Wrist 3: 180°/s. Tool: Typical 1 m/s. / 39.4 in/s.
Repeatability:	+/- 0.1 mm / +/- 0.0039 in (4 mils)
Footprint:	Ø190 mm / 7.5 in
Degrees of freedom:	6 rotating joints
Control box size (WxHxD):	475 mm x 423 mm x 268 mm / 18.7 x 16.7 x 10.6 in
I/O ports:	Controlbox Tool conn.  Digital in 16 2  Digital out 16 2  Analog in 2 2  Analog out 2 -
I/O power supply:	24 V 2A in control box and 12 V/24 V 600 mA in tool
Communication:	TCP/IP 100 Mbit: IEEE 802.3u, 100BASE-TX Ethernet socket & Modbus TCP
Programming:	Polyscope graphical user interface on 12 inch touchscreen with mounting
Noise:	Comparatively noiseless
IP classification:	IP54
Power consumption:	Approx. 350 watts using a typical program
Collaboration operation:	15 Advanced Safety Functions Tested in accordance with: EN ISO 13849:2008 PL d EN ISO 10218-1:2011, Clause 5.4.3
Materials:	Aluminum, ABS plastic, PP plastic
Temperature:	The robot can work in a temperature range of 0-50°C
Power supply:	100-240 VAC, 50-60 Hz
Cabling:	Cable between robot and control box (6 m / 236 in) Cable between touchscreen and control box (4.5 m / 177 in)



DK-5260 Odense S Denmark +45 89 93 89 89

www.universal-robots.com sales@universal-robots.com

